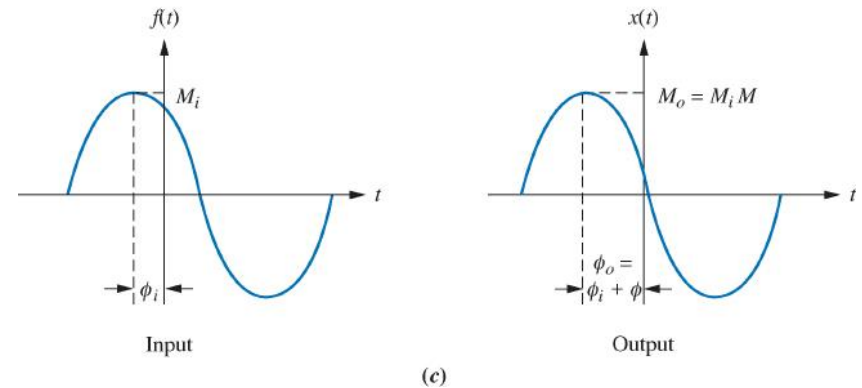
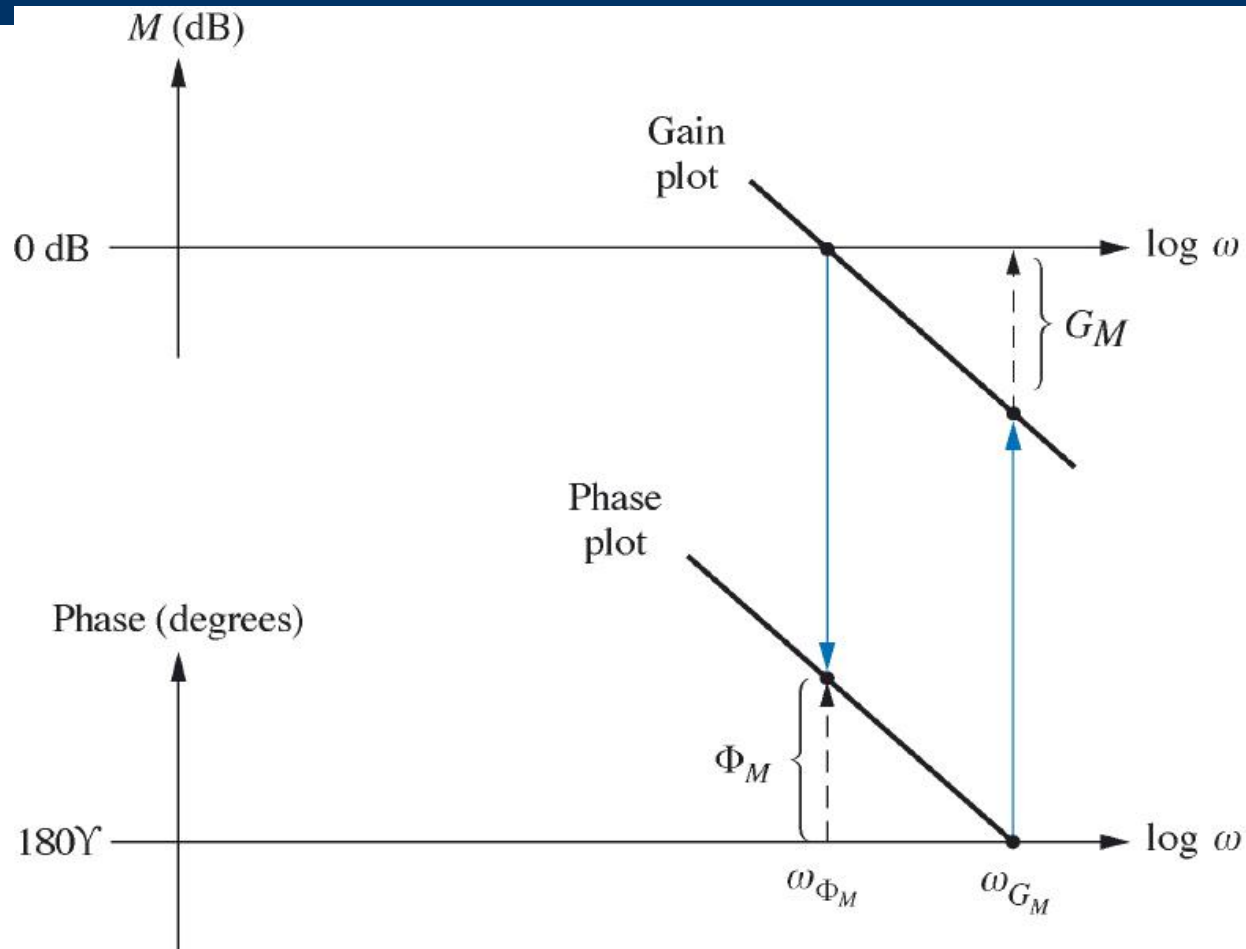


# Frequency Response Techniques

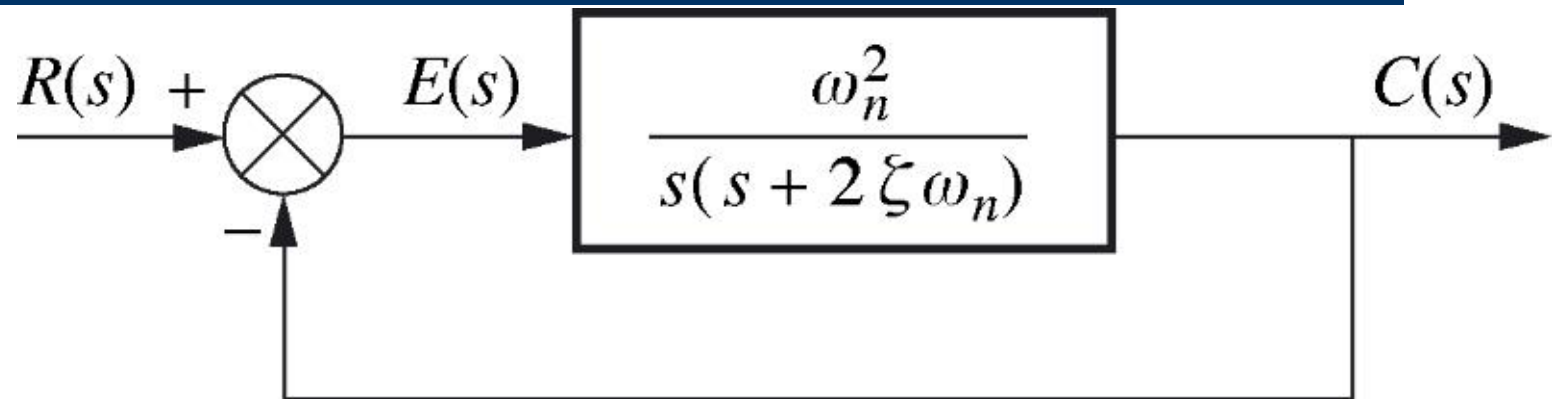


**System & Control Engineering Lab.**  
**School of Mechanical Engineering**

# Stability, Gain margin, Phase margin via Bode Plots



# Relation between Closed-loop Transient and Closed-loop Frequency Responses



the closed-loop transfer function,

$$\frac{C(s)}{R(s)} = T(s) = \frac{\omega_n^2}{s^2 + 2\zeta\omega_n s + \omega_n^2}$$

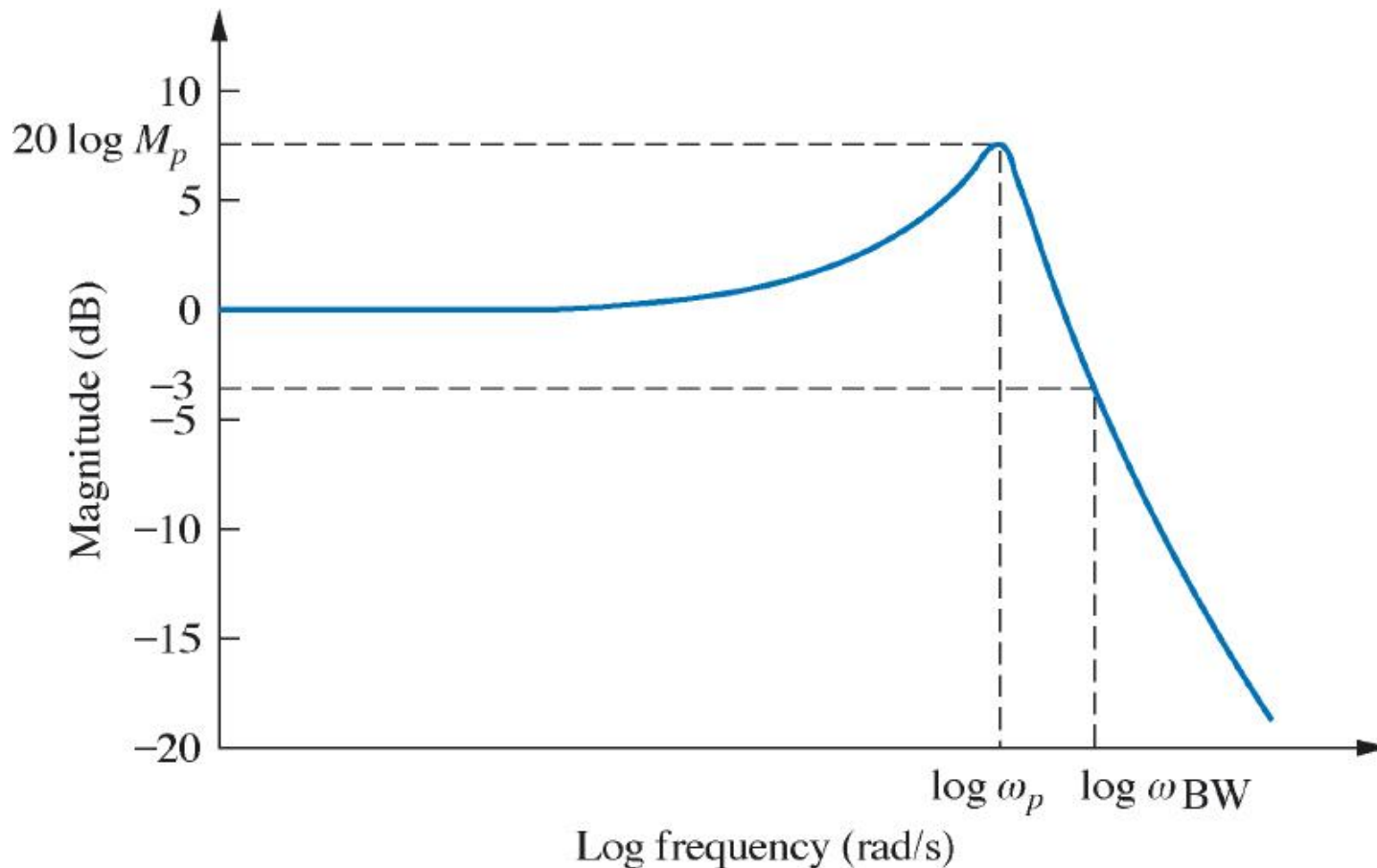
# Relation between Closed-loop Transient and Closed-loop Frequency Responses

$$M = |T(j\omega)| = \frac{\omega_n^2}{\sqrt{(\omega_n^2 - \omega^2)^2 + 4\zeta^2\omega_n^2\omega^2}}$$

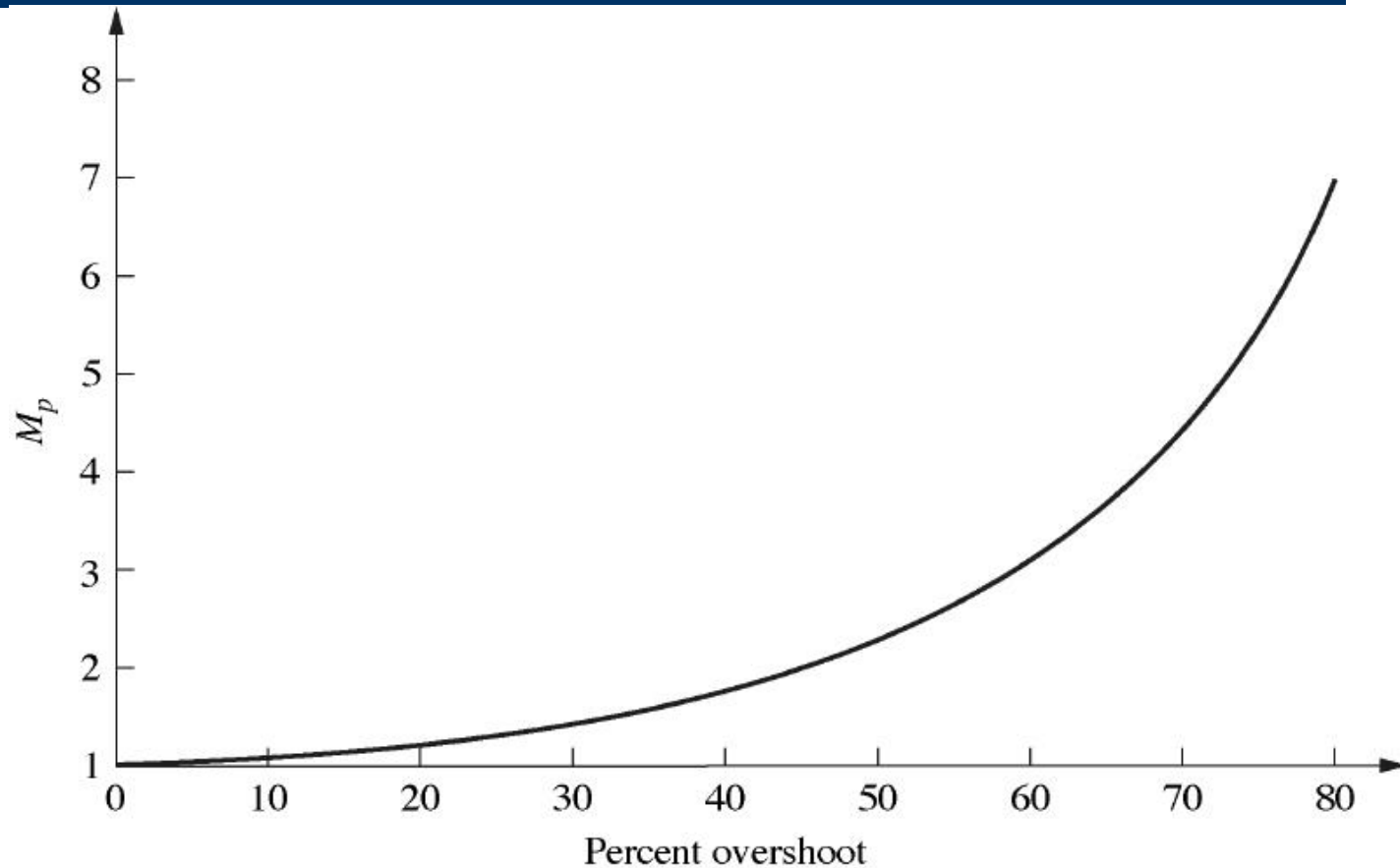
$$M_p = \frac{1}{2\zeta\sqrt{1 - \zeta^2}}$$

$$\omega_p = \omega_n\sqrt{1 - 2\zeta^2}$$

# Relation between Closed-loop Transient and Closed-loop Frequency Responses



# Relation between Closed-loop Transient and Closed-loop Frequency Responses



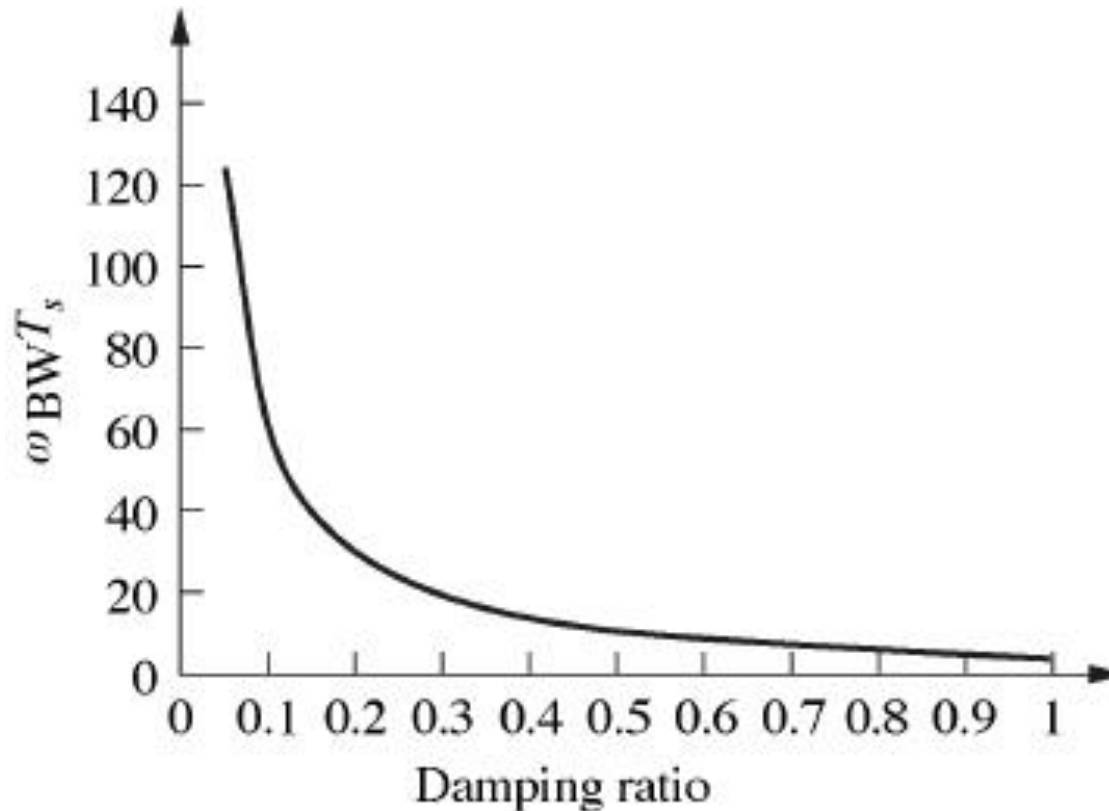
# Response Speed and Closed-loop Frequency Responses

$$\omega_{\text{BW}} = \omega_n \sqrt{(1 - 2\zeta^2) + \sqrt{4\zeta^4 - 4\zeta^2 + 2}}$$

$$\omega_{\text{BW}} = \frac{4}{T_s \zeta} \sqrt{(1 - 2\zeta^2) + \sqrt{4\zeta^4 - 4\zeta^2 + 2}}$$

$$\omega_{\text{BW}} = \frac{\pi}{T_p \sqrt{1 - \zeta^2}} \sqrt{(1 - 2\zeta^2) + \sqrt{4\zeta^4 - 4\zeta^2 + 2}}$$

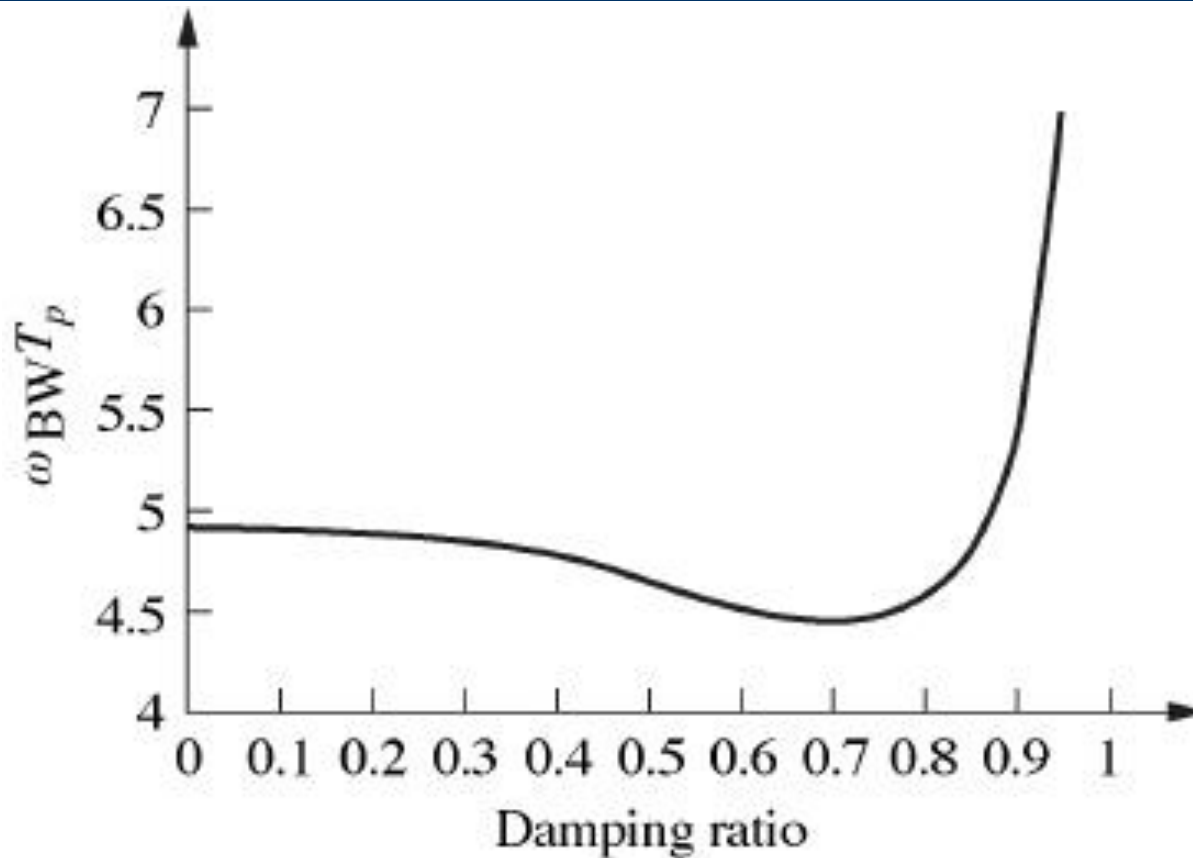
# Response Speed and Closed-loop Frequency Responses



(a)

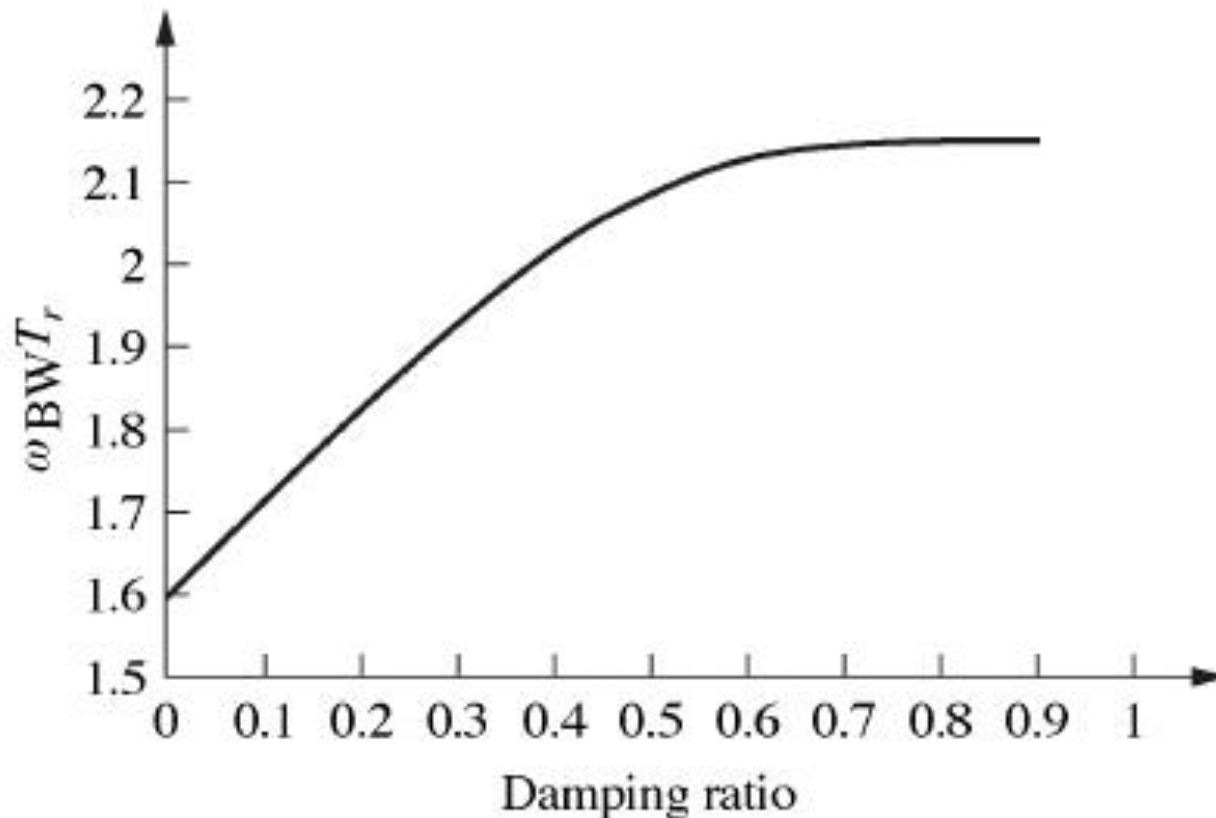


# Response Speed and Closed-loop Frequency Responses



(b)

# Response Speed and Closed-loop Frequency Responses



(c)