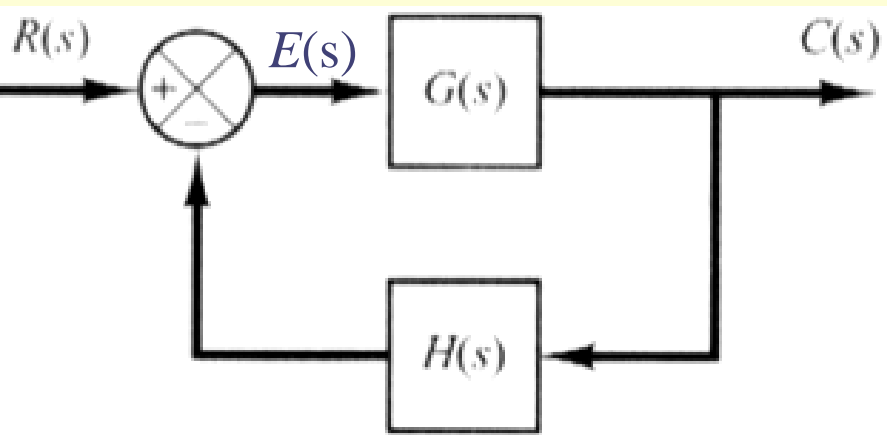


# High-Order Systems



# Transient Response of High-Order Systems



From block diagram

$$C(s) = G(s)E(s)$$

$$E(s) = R(s) - H(s)C(s)$$

$$\frac{C(s)}{G(s)} = R(s) - H(s)C(s)$$

Closed-loop transfer function is

$$\frac{C(s)}{R(s)} = \frac{G(s)}{1 + GH(s)}$$

# Transient Response of High-Order Systems

when  $G(s) = \frac{p(s)}{q(s)}$  and  $H(s) = \frac{n(s)}{d(s)}$

Thus, closed-loop transfer function is

$$\frac{C(s)}{R(s)} = \frac{G(s)}{1 + GH(s)} = \frac{p(s)/q(s)}{1 + (p(s)/q(s))(n(s)/d(s))}$$

$$\frac{C(s)}{R(s)} = \frac{p(s)d(s)}{q(s)d(s) + p(s)n(s)}$$

when  $p(s), q(s), n(s)$  and  $d(s)$  – polynomial  $s$  in  $s$

# Transient Response of High-Order Systems

or in this form

$$\frac{C(s)}{R(s)} = \frac{b_0 s^m + b_1 s^{m-1} + \dots + b_{m-1} s + b_m}{a_0 s^n + a_1 s^{n-1} + \dots + a_{n-1} s + a_n}, \quad (m \leq n)$$

or partial fraction form

$$\frac{C(s)}{R(s)} = \frac{K(s + z_1)(s + z_2) \cdots (s + z_m)}{(s + p_1)(s + p_2) \cdots (s + p_n)}$$

# Transient Response of High-Order Systems

$$C(s) = \frac{K(s + z_1)(s + z_2)\cdots(s + z_m)}{(s + p_1)(s + p_2)\cdots(s + p_n)} R(s) \quad \text{Eq.1}$$

for unit-step input

Case I all real closed-loop poles in eq.1

$$C(s) = \frac{a}{s} + \sum_{i=1}^n \frac{a_i}{s + p_i}$$

when  $a_i$  is part of pole at  $s = -p_i$

# Transient Response of High-Order Systems

## Example

$$C(s) = \frac{200}{s^3 + 31s^2 + 230s + 200} \cdot \frac{1}{s} = \frac{200}{(s+1)(s+10)(s+20)} \cdot \frac{1}{s}$$

Thus  $p_{1,2,3} = -1, -10, -20$ ;  $K = 1$

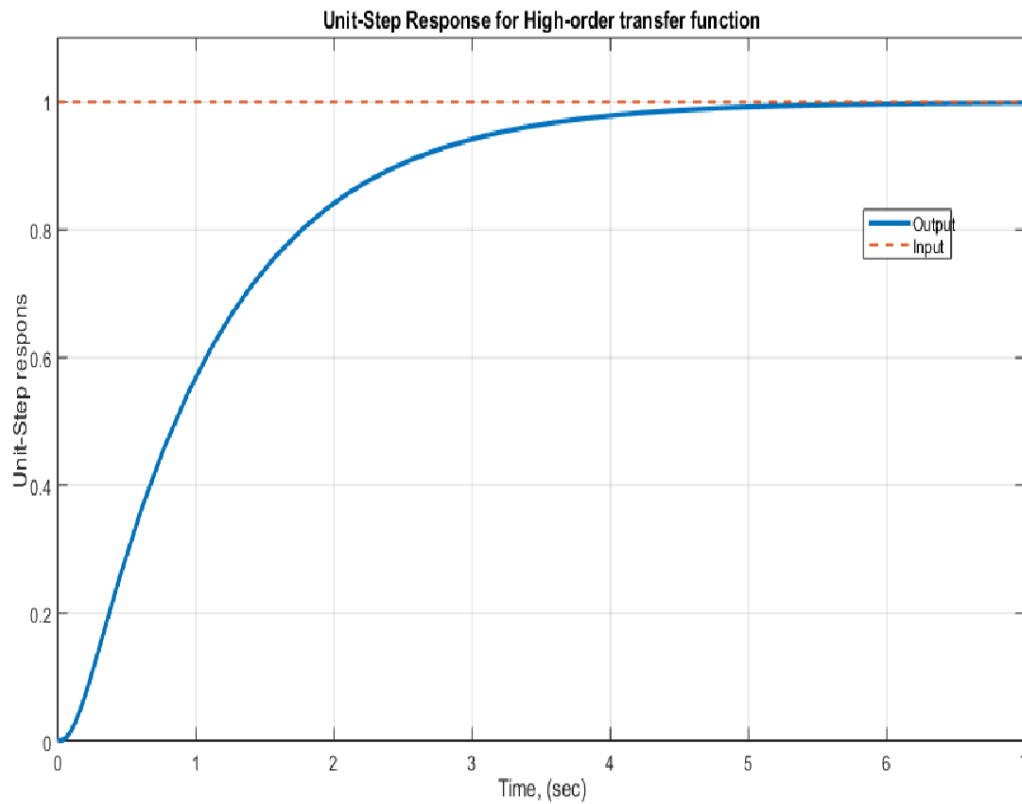
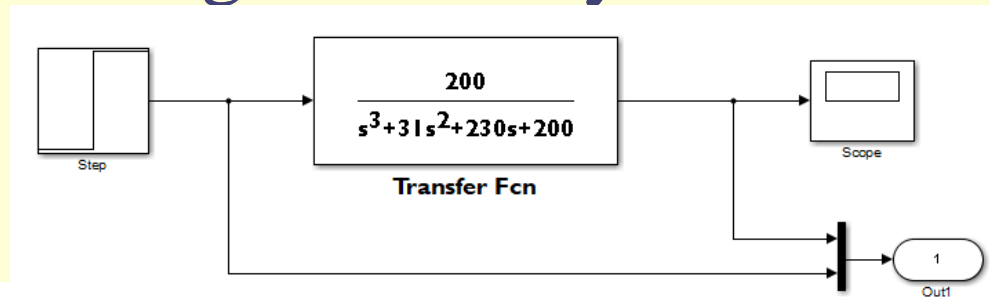
Partial-fraction expansion

$$C(s) = \frac{1}{s} + \frac{1.1696}{s+1} - \frac{2.222}{s+10} + \frac{1.0576}{s+20}$$

Solution

$$c(t) = 1 + 1.1696e^{-t} - 2.222e^{-10t} + 1.0576e^{-20t}$$

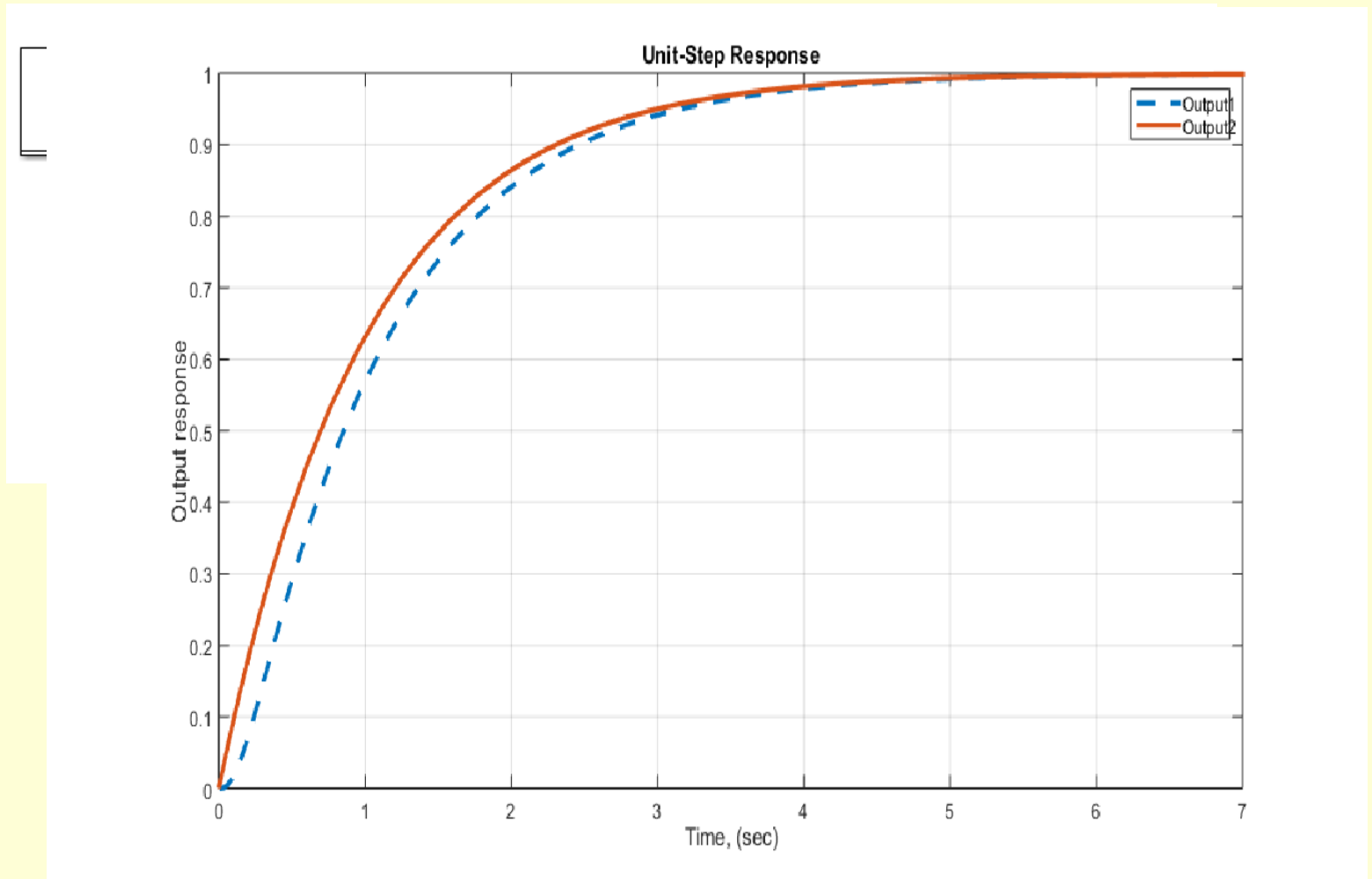
# Transient Response of High-Order Systems



Dominant pole

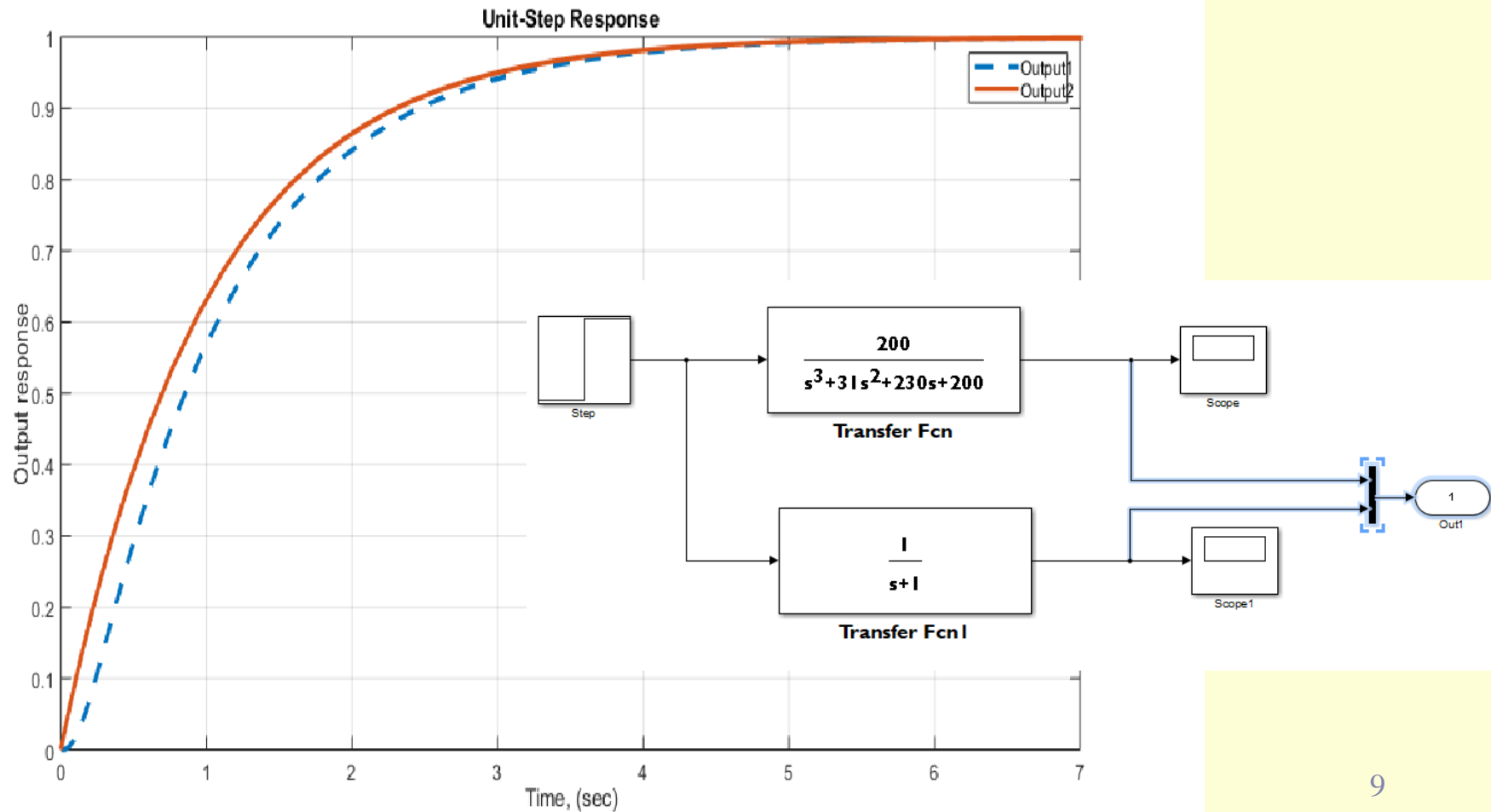
$$p_1 = -1$$

# Transient Response of High-Order Systems





# Transient Response of High-Order Systems



# Transient Response of High-Order Systems

Case II Real closed-loop poles and pair of complex-conjugate poles for unit-step input

$$C(s) = \frac{a}{s} + \sum_{j=1}^q \frac{a_j}{s + p_j} + \sum_{k=1}^r \frac{b_k (s + \zeta_k \omega_k) + c_k \omega_k \sqrt{1 - \zeta_k^2}}{s^2 + 2\zeta_k \omega_k s + \omega_k^2}$$

when  $q + 2r = n$



# Transient Response of High-Order Systems

Solution

$$c(t) = a + \sum_{j=1}^q a_j e^{-pt} + \sum_{k=1}^r b_k e^{-\zeta_k \omega_k t} \cos \omega_k \sqrt{1 - \zeta_k^2} t$$
$$+ \sum_{k=1}^r c_k e^{-\zeta_k \omega_k t} \sin \omega_k \sqrt{1 - \zeta_k^2} t$$

# Transient Response of High-Order Systems

Example: Unit-step input

$$C(s) = \frac{50}{s^3 + 12s^2 + 25s + 50} \cdot \frac{1}{s} = \frac{50}{(s+10)(s^2 + 2s + 5)} \cdot \frac{1}{s}$$

Thus  $p_1 = -10, p_{2,3} = -1 \pm 2j; K = 1$

Partial-fraction expansion

$$C(s) = \frac{1}{s} + \frac{0.625}{s+10} + \frac{(-8-32j)}{s+1+2j} + \frac{(-8+32j)}{s+1-2j}$$

$$C(s) = \frac{1}{s} + \frac{0.625}{s+10} + \frac{-16(s+1)-128}{(s+1)^2 + 2^2}$$

# Transient Response of High-Order Systems

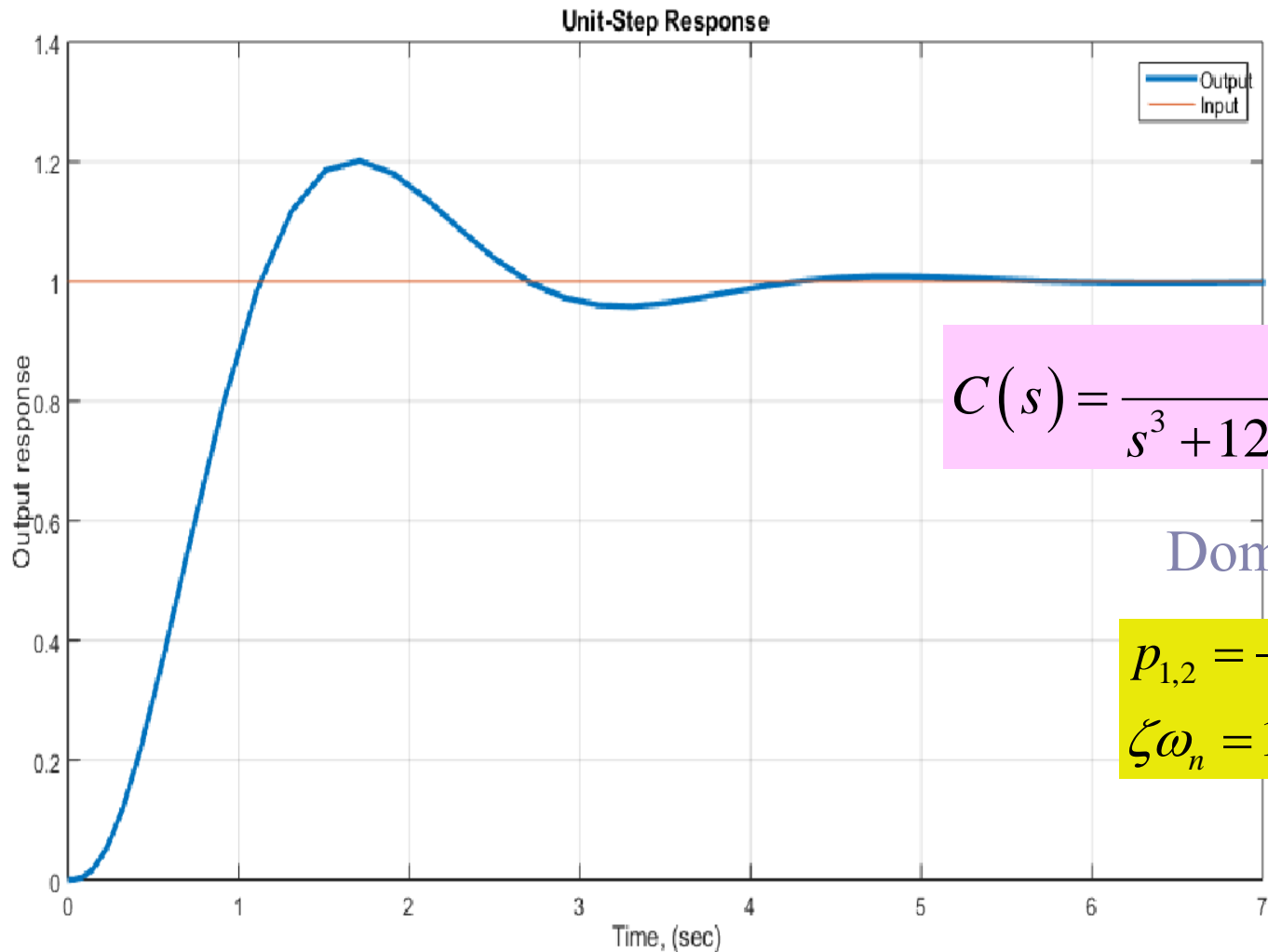
Partial-fraction expansion

$$C(s) = \frac{1}{s} + \frac{0.625}{s+10} - \frac{16(s+1)}{(s+1)^2 + 2^2} - \frac{64(2)}{(s+1)^2 + 2^2}$$

Solution

$$c(t) = 1 + 0.625e^{-10t} - 16e^{-t} \cos 2t - 64e^{-t} \sin 2t$$

# Transient Response of High-Order Systems



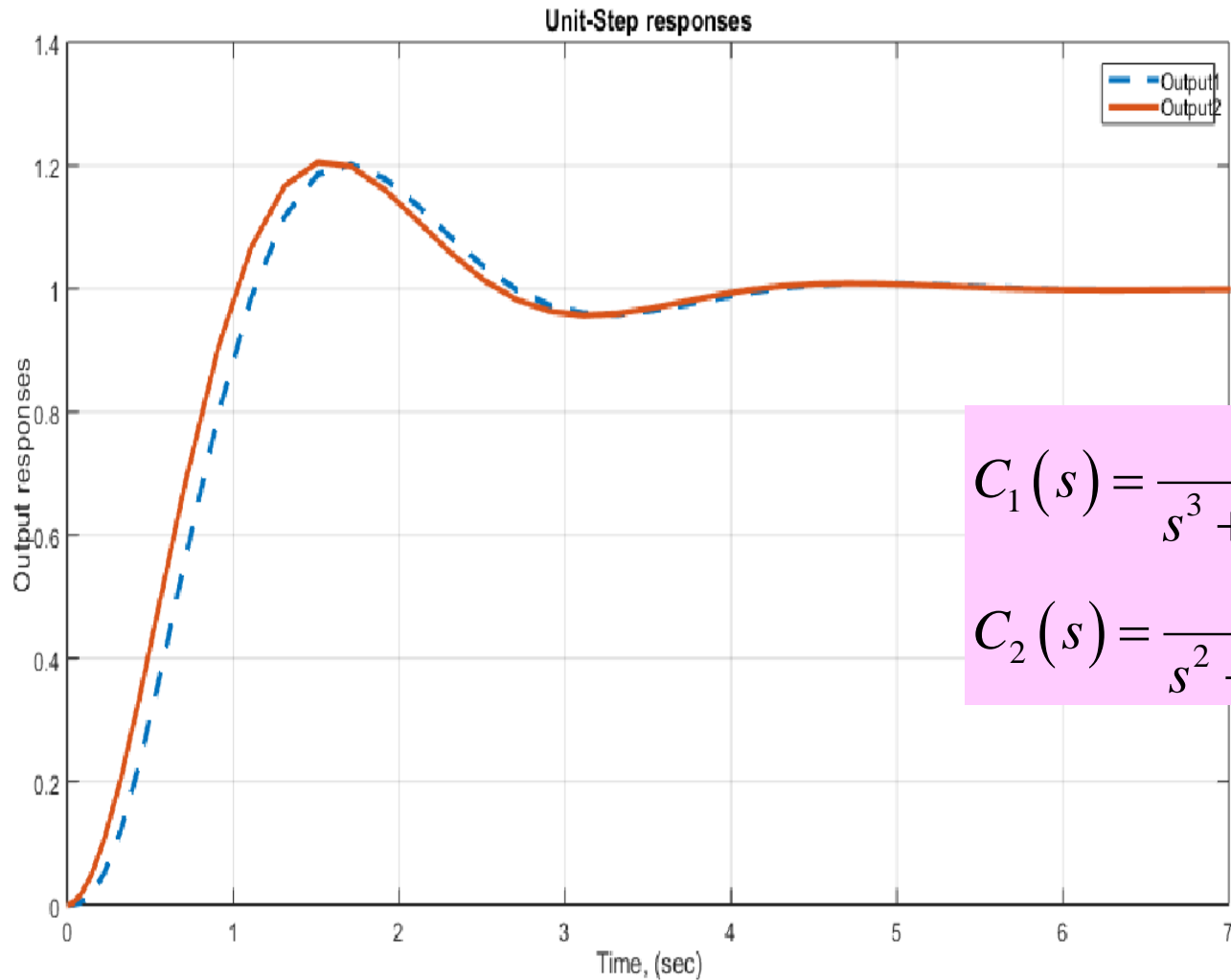
$$C(s) = \frac{50}{s^3 + 12s^2 + 25s + 50} \cdot \frac{1}{s}$$

Dominant poles

$$p_{1,2} = -1 \pm 2i$$

$$\zeta\omega_n = 1; \omega_d = 2 \text{ rad/sec}$$

# Transient Response of High-Order Systems



$$C_1(s) = \frac{50}{s^3 + 12s^2 + 25s + 50} \cdot \frac{1}{s}$$
$$C_2(s) = \frac{5}{s^2 + 2s + 5} \cdot \frac{1}{s}$$